

# Advanced Multiprocessor Programming: Data-Structures Part 1

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A first data structure: List-based set

General issues and concerns:

- Coarse-grained vs. fine-grained synchronization
- Safety and liveness properties
- Progress guarantees
- Data structure: Algorithms and complexity

The trivial solution: Use lock to protect all data structure operations

- Acquire lock when data structure is accessed (especially updated): Each method call acquires and releases
- **Likely major scalability bottleneck!**
  - Only one thread can access data-structure at any time
    - Even for read accesses!
  - No progress guarantees
    - Thread holding a lock may block other threads indefinitely
  - But linearizable (when lock is acquired)

Can we do better?

# Fine-grained synchronization

- Decouple parts of the data-structure
  - multiple locks
- Get rid of locks altogether
  - Use higher-consensus operations instead (atomics)
- Provide progress guarantees

# Liveness properties

- Deadlock-free
- Starvation-free
- Non-blocking
  - No thread can block other threads  
(Threads not actively participating at the moment shall not hinder other threads from progressing)
  - All threads may require an unbounded number of steps
- Lock-free
  - At least one thread progresses in a bounded number of steps
- Wait-free
  - All threads progress in a bounded number of steps

# Correctness condition: Linearizability

- Operation appears to take effect as a single, atomic step somewhere during the execution
- Operations on data-structure appear as atomic operations to the outside
  - (other, concurrent method calls)
- Tricky to achieve
  - The combination of two linearizable operations is not necessarily linearizable (an insert combined with a delete will not be atomic to the outside observer)

For each implemented operation:

- Look at the outcome (return value)
- Show that there is some instant (a linearization point) during the execution of the operation where this outcome is correct in the linearized history (sequence of linearization points)
- The linearization point is sometimes a specific operation, but sometimes depends on the history (concurrent execution of other operations)

# The data structure: List-based set

Set data-structure operations:

- `bool add(item)`
  - Add item to the set (if not already in set)
  - Return `true` if item was added, `false` if already existing
- `bool remove(item)`
  - Remove item from set
  - Return `true` on success, `false` if item was not found
- `bool contains(item)`
  - Check whether item exists in set

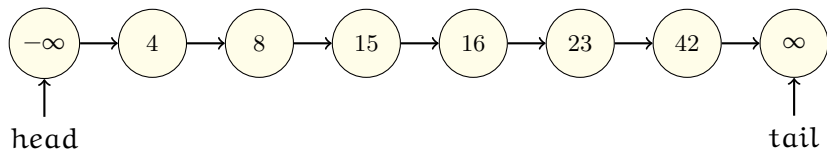
Implementation as ordered, linked list, items identified by key drawn from an ordered universe. Note: In code snippets, we do not distinguish between `item` and `key`

In terms of sequential complexity, not a good data structure, all operations are  $O(n)$  and some require  $\Omega(n)$



# List-based set: Data structure

- Sorted, linked list of node elements
- Elements identified by unique key from ordered universe
- Items stored in nodes are comparable by key
- Sentinel nodes for head and tail
- Head and tail contain maximum and minimum key values ( $-\infty$  and  $\infty$ )



# List-based set: Assumptions and Invariants

- Assumptions
  - Freedom from interference  
(only operations **add**, **remove** and **contains** may modify nodes)
  - Garbage collection available
- Invariants: Properties that hold initially and are maintained by any (concurrent) operation; no thread can take a step that makes an invariant false.
  - Sentinel nodes are neither added nor removed
  - Nodes are sorted by item (key)
  - Items are unique
  - Item is in the set iff it is reachable from the head

# List-based set with coarse-grained locking

- Single, global lock
- Acquired at beginning of each method call
- Released at the end
- Similar to a sequential implementation

```
Node* head;
mutex m;

bool add(T item) {
    // C++11 style locking
    lock_guard<mutex> g(m);

    // Search for item or successor
    Node* pred = head;
    Node* curr = pred->next;
    while (curr->item < item) {
        pred = curr;
        curr = curr->next;
    }

    // Item already in set
    if (item == curr->item) return false;

    // Add item to set
    Node* n = new Node(item, curr);
    pred->next = n;

    return true; // Done
} // end of lock scope
```

# List-based set with coarse-grained locking: Properties

- Obviously correct
- Execution is essentially sequential
- Linearization point
  - The instant the lock is acquired
- Liveness
  - Same as the lock implementation
- No progress guarantees!  
(Thread holding the lock may stall, progress of all other threads blocked)

# Relaxation: Reader-Writer Lock

- Use Reader-Writer lock instead of a normal lock
- Allows concurrent read accesses
- Better performance if **contains** is the most common operation
  - Typically the case

```
Node* head;
rw_mutex m;

bool contains(T item) {
    // Pseudocode
    lock_guard<mutex> g(m.read_lock());

    // Search for item
    Node* curr = head;
    while (curr->item < item) {
        curr = curr->next;
    }

    if (item == curr->item)
        return true; // element in set
    else
        return false; // not in set
} // end of lock scope
```

# Reader-Writer Lock: Properties

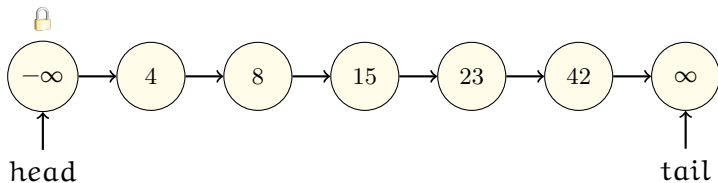
- Multiple **contains** checks can be performed at the same time
- Linearization point
  - The instant the lock is acquired
- Liveness
  - Same as the lock implementation
  - Still no progress guarantees!  
(A single writer may stall all other threads)
  - Special case: No writers  $\rightarrow$  wait-free  
(if reader-lock implementation is wait-free)

- Split object into independently synchronized components
- Method calls only interfere when trying to access the same component at the same time

→ Instead of a global lock, use a lock per node

# List-based set with fine-grained locks: add(16)

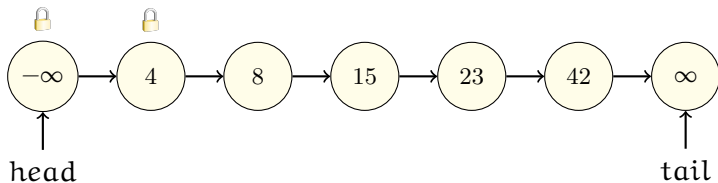
- Locks acquired in hand-over-hand manner
- New item inserted between locks





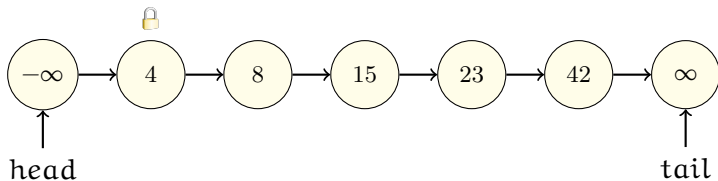
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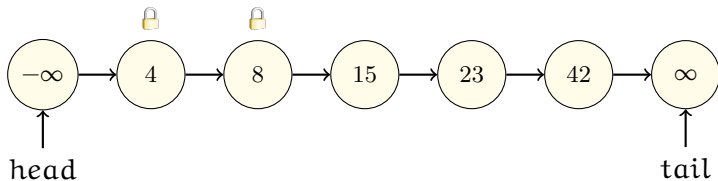
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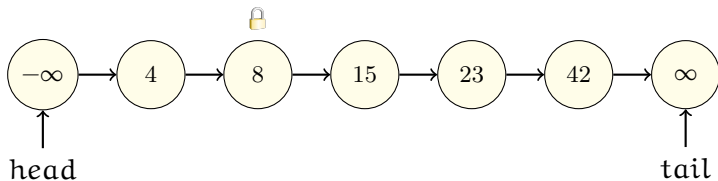
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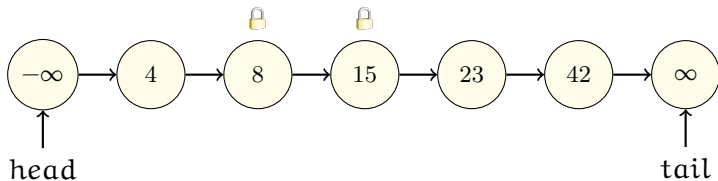
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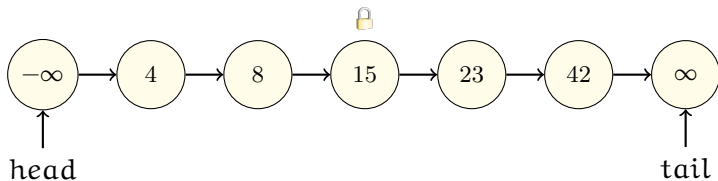
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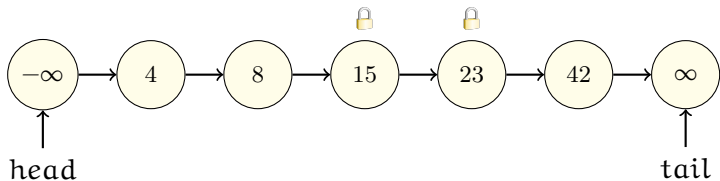
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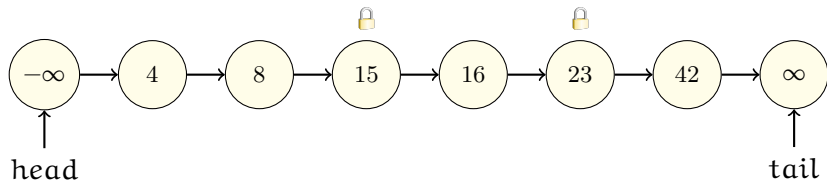
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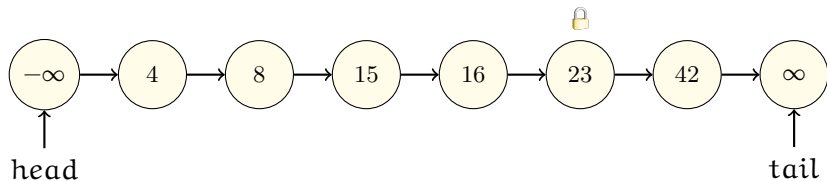
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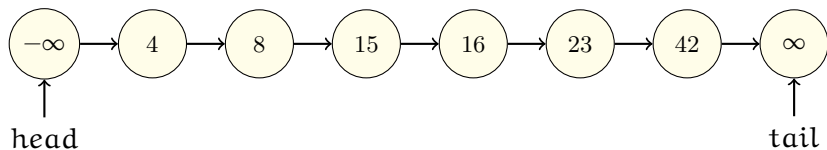
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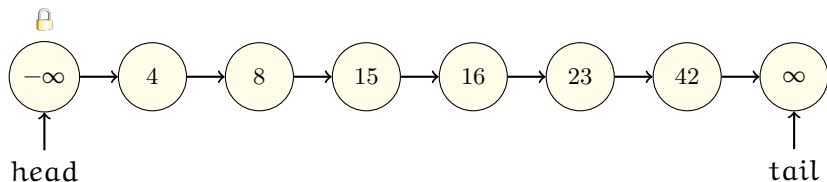
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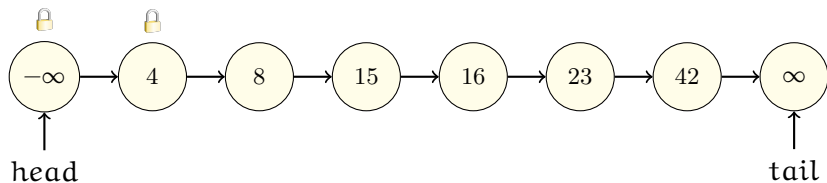
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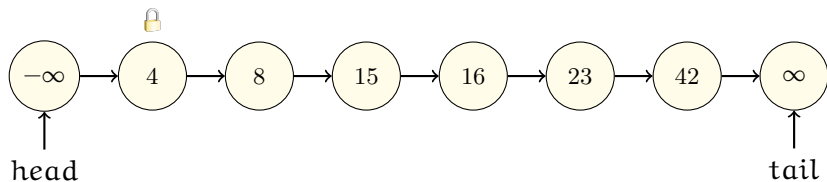
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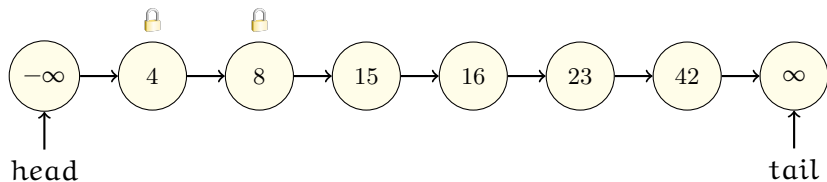
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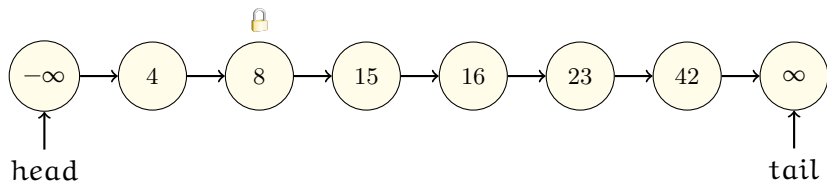
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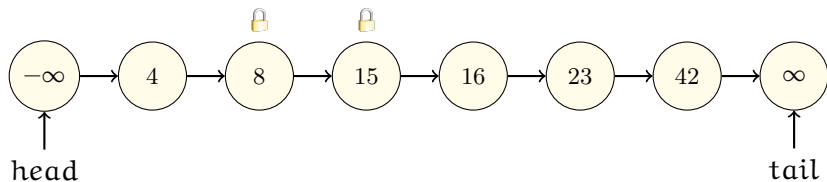
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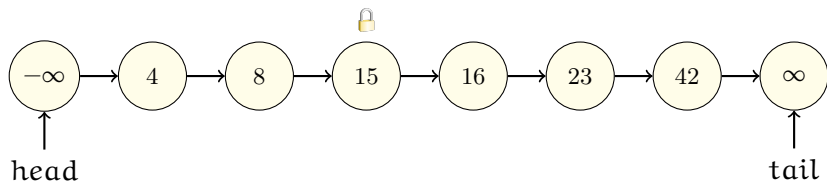
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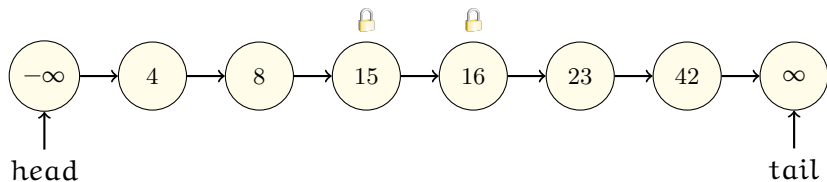
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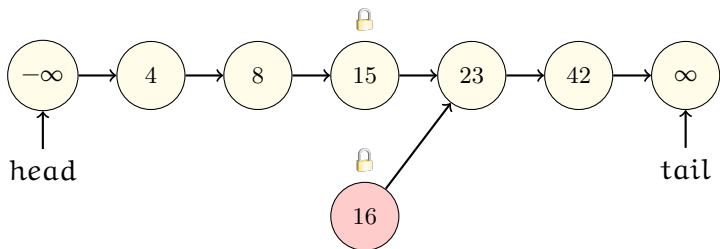
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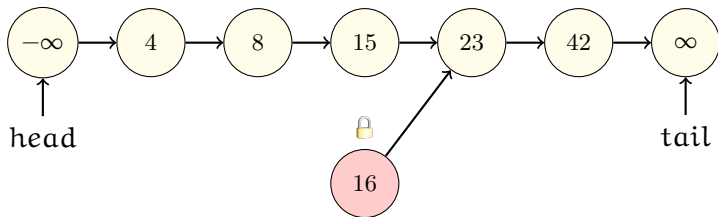
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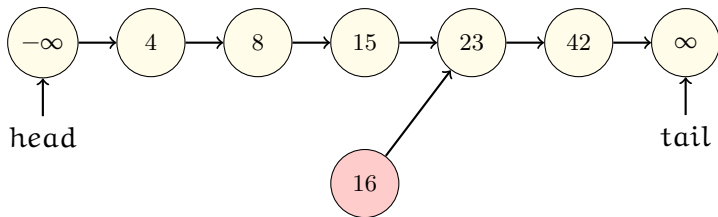
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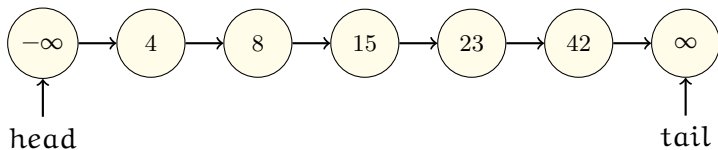
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# List-based set with fine-grained locks

```
Node* head;
struct Window {
    Node* pred;
    Node* curr;
}

Window find(T item) {
    // Search for item or successor
    Node* pred = head;
    pred->lock();

    // Exception safety for locks ignored
    // for simplicity
    Node* curr = pred->next;
    curr->lock();

    while (curr->item < item) {
        pred->unlock();
        pred = curr;
        curr = curr->next;
        curr->lock();
    }

    return Window(pred, curr);
}

void unlock(Window w) {
    pred->unlock();
    curr->unlock();
}
```

```
bool contains(T item) {
    Window w = find(item);
    bool found = item == w.curr->item;
    unlock(w);
    return found;
}

bool add(T item) {
    Window w = find(item);
    if (item == w.curr->item) {
        unlock(w);
        return false;
    }
    Node* n = new Node(item, w.curr);
    w.pred->next = n;
    unlock(w);
    return true;
}

bool remove(T item) {
    Window w = find(item);
    if (item != w.curr->item) {
        unlock(w);
        return false;
    }
    w.pred->next = w.curr->next;
    unlock(w);
    delete(w.curr); // safe to delete
    return true;
}
```

# List-based set with fine-grained locking: Invariants

- Sentinels are never added or removed
- Nodes are sorted by item
- Each item occurs exactly once
- An item is in the set iff it is reachable from head



- Locks are always acquired in the same order  
→ deadlock-free
- If the locks are starvation-free, so is the set
- No progress guarantees
- Limited concurrency  
(A thread having lock to a small item early in the list blocks other threads looking for larger items)

Linearization points:

Outcome: Item in set

- Linearize when item containing element is locked  
(Cannot be removed while locked)

Outcome: Item not in set

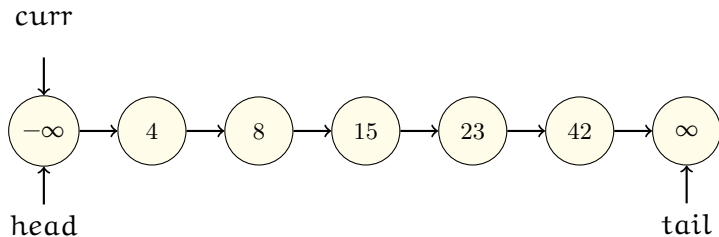
- Linearize when node containing next-higher item is locked  
(Predecessor node cannot be inserted while an item is locked)

Idea:

- Search for a component without acquiring locks
- Lock the found nodes
- Confirm whether the nodes are correct: Validate that they are still reachable, and that `pred` points to `curr`
- On failure, release locks and start over
- Requires good validation!

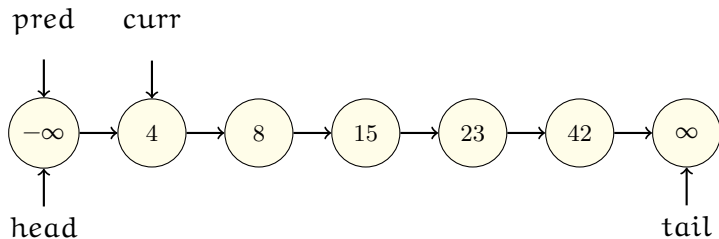
# List-based set with optimistic synchronization: add(16)

- Search for item without locking



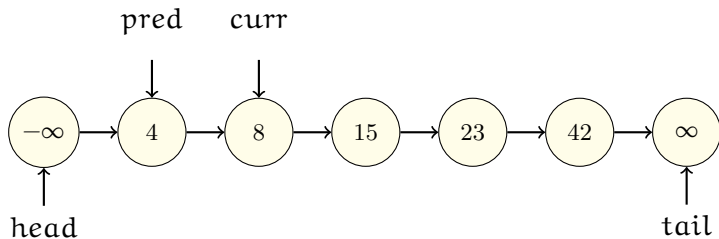
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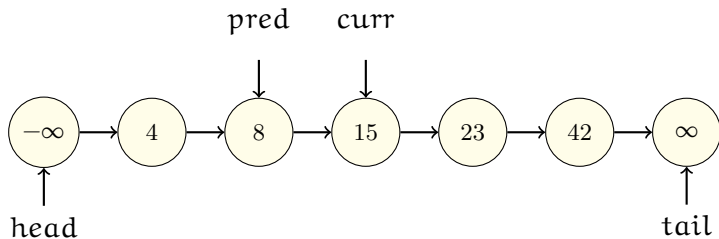
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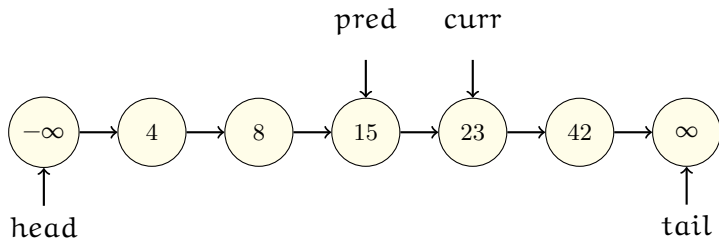
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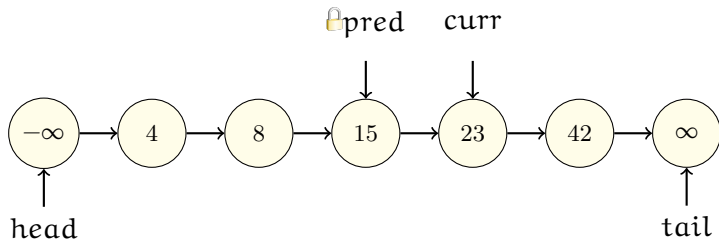
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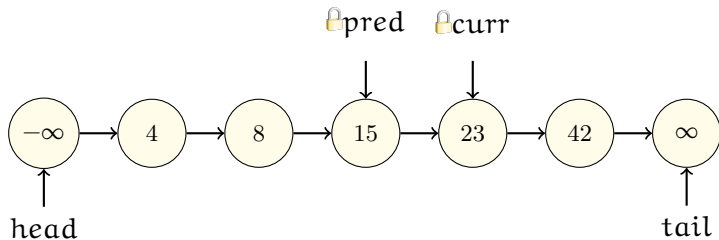
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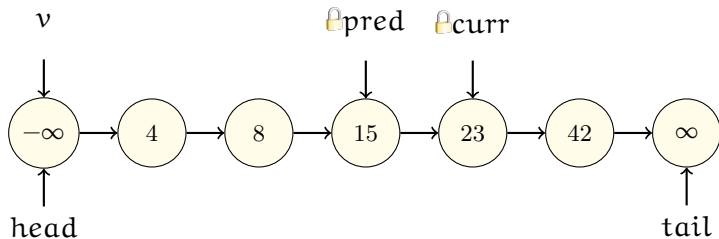
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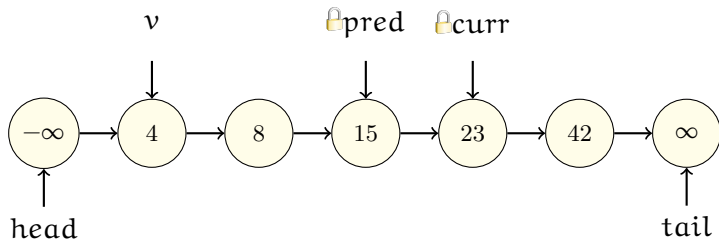
# List-based set with optimistic synchronization: add(16)

- Search for item without locking
- Lock item
- Validate by searching for item again



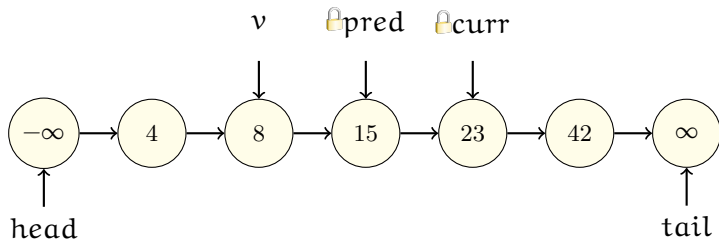
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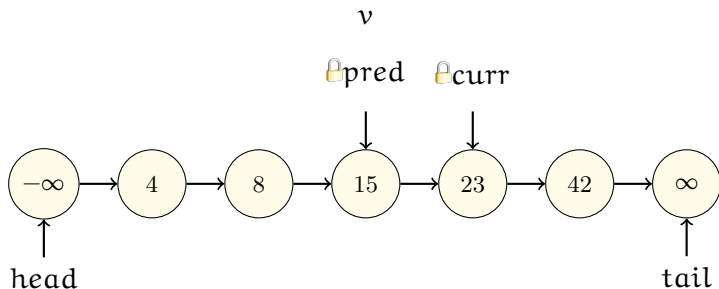
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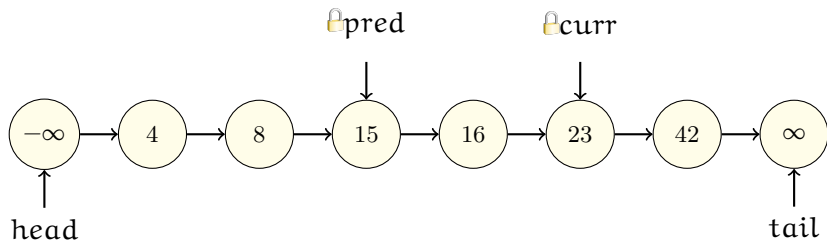
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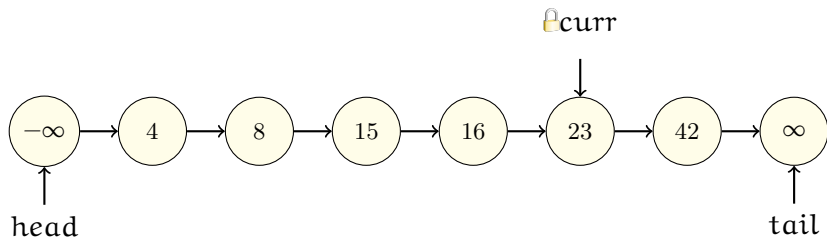
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- Validate by searching for item again
- Add item



# List-based set with optimistic synchronization: add(16)

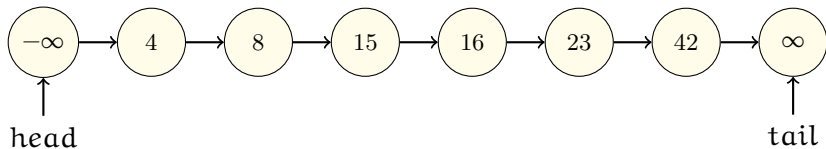
- Search for item without locking
- Lock item
- Validate by searching for item again
- Add item
- Unlock





# List-based set with optimistic synchronization: add(16)

- Search for item without locking
- Lock item
- Validate by searching for item again
- Add item
- Unlock



# List-based set with optimistic synchronization

```
Node* head;
struct Window {
    Node* pred;
    Node* curr;
}

void lock(Window w) {
    pred->lock();
    curr->lock();
}

void unlock(Window w) {
    pred->unlock();
    curr->unlock();
}

bool validate(Window w) {
    Node* n = head;
    while (n->item <= w.pred->item) {
        if (n == w.pred)
            return n->next == w.curr;

        n = n->next;
    }
    return false;
}
```

```
Window find(T item) {
    while (true) {
        // Search for item or successor
        Node* pred = head;
        Node* curr = pred->next;

        while (curr->item < item) {
            pred = curr;
            curr = curr->next;
        }

        Window w(pred, curr);
        lock(w);
        if (validate(w)) return w;
        unlock(w);
    }
}
```

# List-based set with optimistic synchronization

```
bool contains(T item) {
    // Identical to fine-grained locking:

    Window w = find(item);
    bool found = item == w.curr->item;
    unlock(w);
    return found;
}

bool add(T item) {
    // identical to fine-grained locking

    Window w = find(item);
    if (item == w.curr->item) {
        unlock(w);
        return false;
    }
    Node* n = new Node(item, w.curr);
    w.pred->next = n;
    unlock(w);
    return true;
}
```

```
bool remove(T item) {
    Window w = find(item);
    if (item != w.curr->item) {
        unlock(w);
        return false;
    }
    w.pred->next = w.curr->next;
    unlock(w);

    // Deletion of nodes would be unsafe!
    // delete(w.curr);

    return true;
}
```

# List-based set with optimistic synchronization: Properties

- Nodes may be traversed even though they have been removed
- Rely on garbage collection for removed nodes
  - **Manual memory reclamation is difficult**  
(How can we know that no thread currently reads a node?)
- Previous invariants still apply
  - Sentinels are never added or removed
  - Nodes are sorted by the item
  - Each item occurs exactly once
  - An item is in the set iff it is reachable from head
    - But only if validated!
- Freedom of interference essential: **next** field only changed by operations on the list

- Deadlock-free
  - Locks are always acquired in the same order
  - On failed validation both locks are freed
- Not starvation-free!
  - Validation might fail all the time as other threads add and remove nodes
- No progress guarantees!  
(But many threads can work concurrently on different items in list)

Linearization points:

Outcome: Item in set

- Linearize when item containing element is successfully validated

Outcome: Item not in set

- Linearize when node containing next-higher item is validated

Disadvantages of optimistic synchronization (aka: Speculation):

- Need to acquire locks for `contains` call  
(`contains` calls are typically more common than `add` or `remove` calls)
- Even though `contains` does not modify the list
- List is traversed twice, so computational overhead is doubled

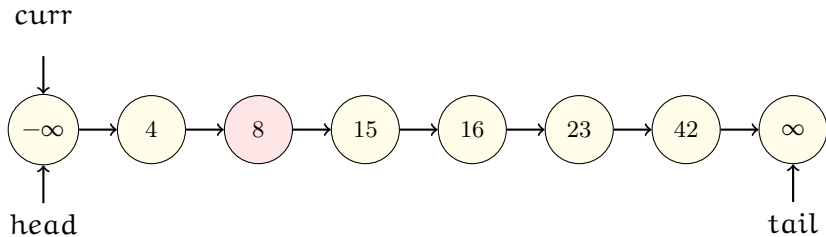
Idea: Be lazy and postpone some hard operations, or get help from other threads

- Split **remove** operation into two parts
  - Logical removal
    - Introduce additional marked flag for each node
    - A node is in the set iff it is reachable and not marked
  - Physical removal
    - Redirect next pointer of predecessor node



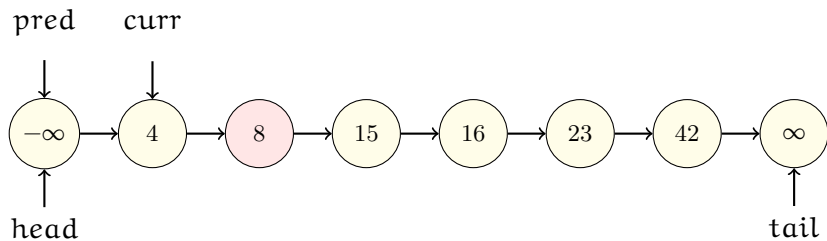
# List-based set with lazy synchronization: `remove(16)` call

- Search for item without locking



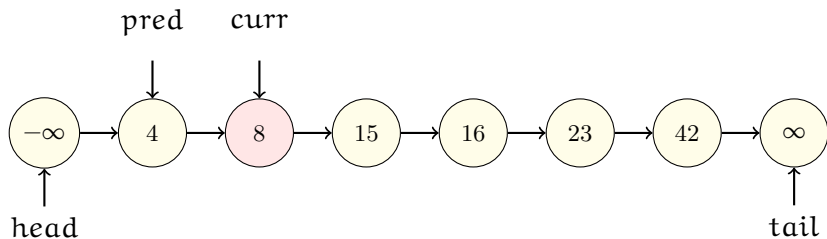
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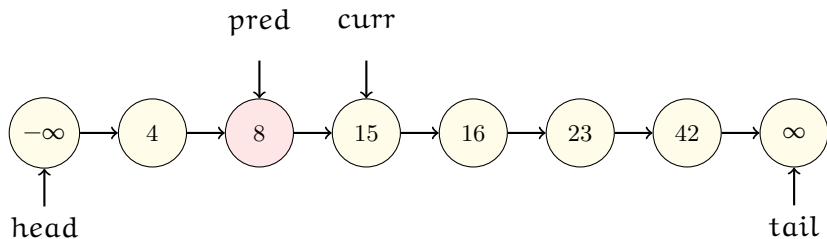
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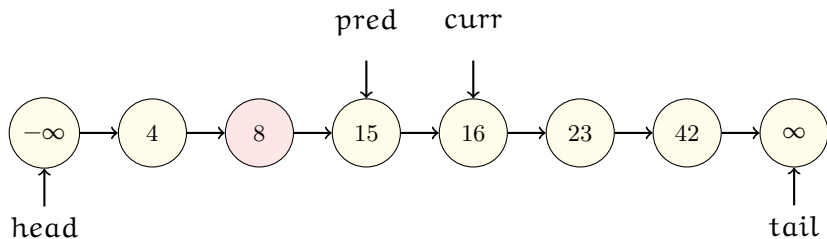
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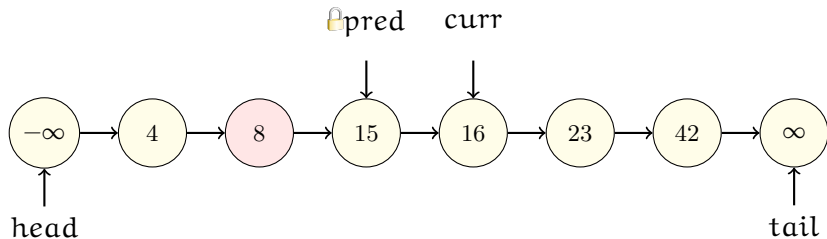
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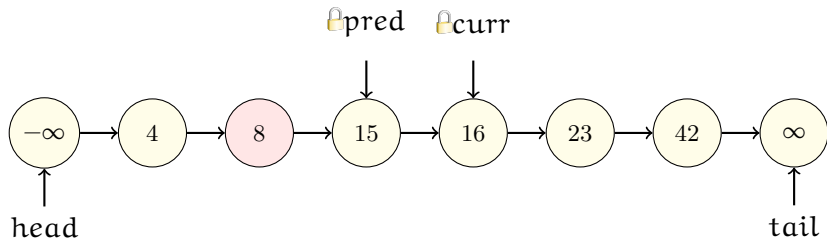
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- Search for item without locking
- Lock item



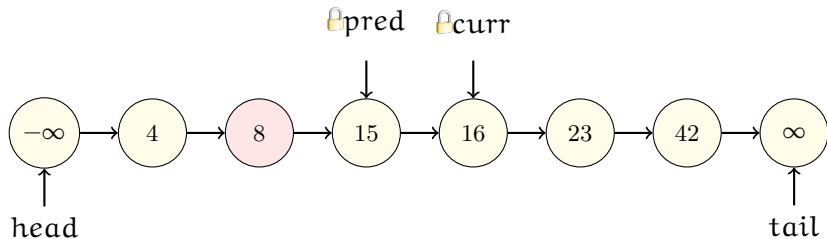
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# List-based set with lazy synchronization: `remove(16)` call

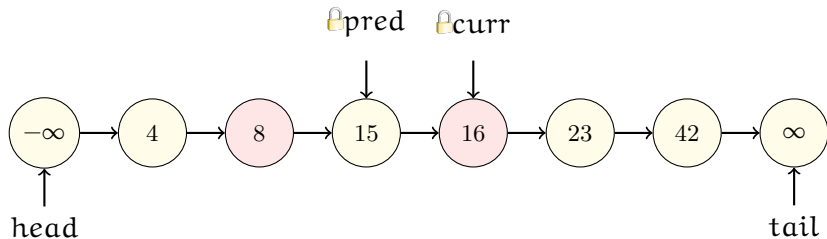
- Search for item without locking
- Lock item
- Verify by checking marked flags of items





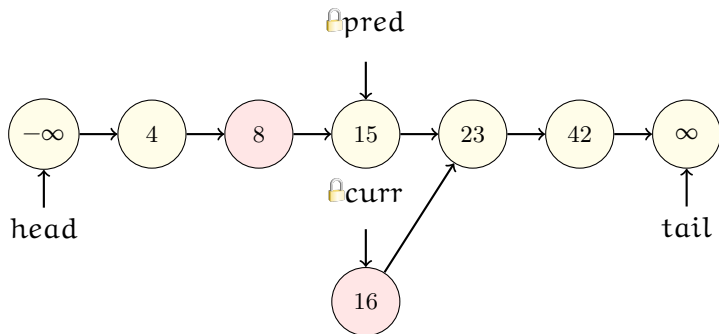
# List-based set with lazy synchronization: `remove(16)` call

- Search for item without locking
- Lock item
- Verify by checking marked flags of items
- Mark item as logically removed



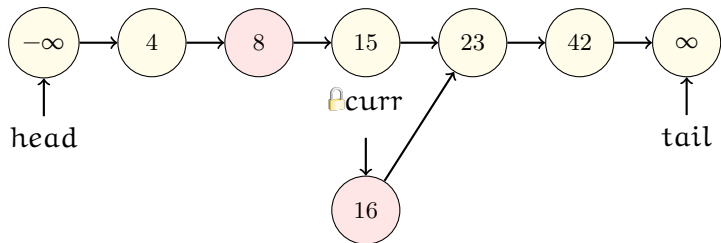
# List-based set with lazy synchronization: `remove(16)` call

- Search for item without locking
- Lock item
- Verify by checking marked flags of items
- Mark item as logically removed
- Unlink item



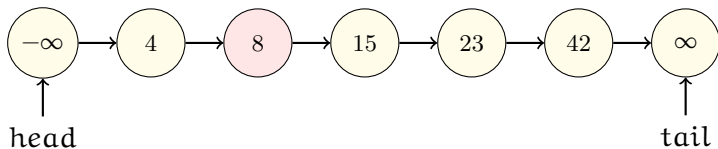
# List-based set with lazy synchronization: `remove(16)` call

- Search for item without locking
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- Verify by checking marked flags of items
- Mark item as logically removed
- Unlink item
- Unlock



# List-based set with lazy synchronization: `remove(16)` call

- Search for item without locking
- Lock item
- Verify by checking marked flags of items
- Mark item as logically removed
- Unlink item
- Unlock



# List-based set with lazy synchronization

```
Node* head;
struct Window {
    Node* pred;
    Node* curr;
}

Window find(T item) {
    while (true) {
        // Search for item or successor
        Node* pred = head;
        Node* curr = pred->next;

        while (curr->item < item) {
            pred = curr;
            curr = curr->next;
        }

        Window w(pred, curr);
        lock(w);
        if (validate(w)) return w;
        unlock(w);
    }
}

bool validate(Window w) {
    return !w.pred->marked &&
        !w.curr->marked &&
        w.pred->next == curr;
}
```

```
bool contains(T item) {
    Node* n = head;

    while (n->item < item) n = n->next;

    return n->item == item &&
        !n->marked;
}

bool add(T item) {
    // identical to fine-grained locking
}

bool remove(T item) {
    Window w = find(item);
    if (item != w.curr->item) {
        unlock(w);
        return false;
    }
    // logical remove (mark)
    w.curr->marked = true;

    // physical unlink
    w.pred->next = w.curr->next;
    // MUST occur before unlinking in
    // memory!

    unlock(w);
    return true;
}
```

# List-based set with lazy synchronization: Invariants

- Nodes may be traversed even though they have been removed
- We rely on garbage collection for removed nodes
- Sentinels are never added or removed
- Nodes are sorted by the item
- Each item occurs exactly once
- An item is in the set iff
  - it is reachable from head
  - it is not marked

- Deadlock-free
  - Locks are always acquired in the same order
  - On failed validation both locks are freed
  - No locks at all for `contains`
- `add` and `remove` not starvation-free!
  - Validation might fail all the time as other threads `add` and `remove` nodes
- Wait-free `contains` call

# List-based set with lazy synchronization: Linearization

Linearization points:

Outcome: Item in set

`add` Successful validation  
`remove` Flag marked set to `true`  
`contains` Read of marked flag

Outcome: Item not in set

`add` Successful validation of next node  
`remove` Successful validation of next node  
`contains` Earlier of

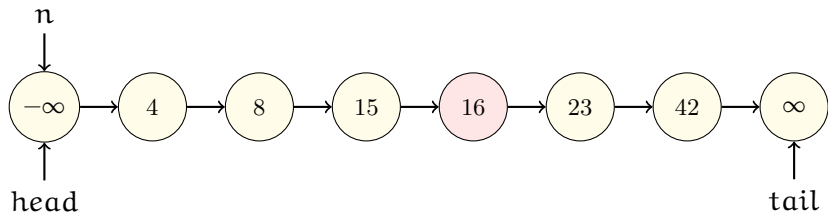
- Point where a removed matching node, or a node with `node->item > item` is found
- Point immediately before a new matching node is added to list



# List-based set with lazy synchronization

Linearization of unsuccessful `contains(16)` call

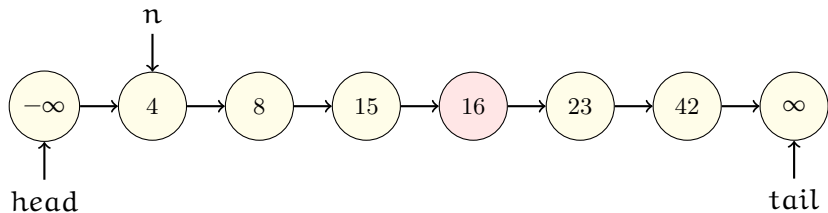
- Search for item without locking



# List-based set with lazy synchronization

Linearization of unsuccessful `contains(16)` call

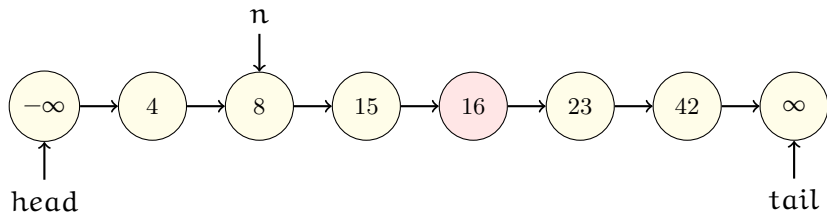
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# List-based set with lazy synchronization

Linearization of unsuccessful `contains(16)` call

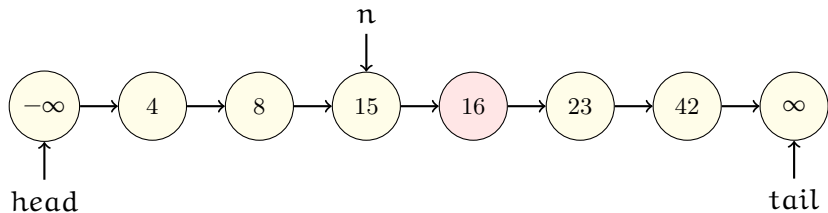
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# List-based set with lazy synchronization

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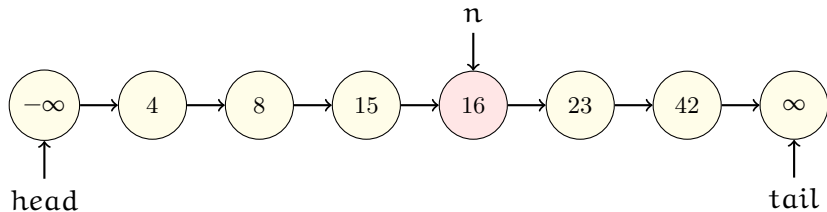
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# List-based set with lazy synchronization

Linearization of unsuccessful `contains(16)` call

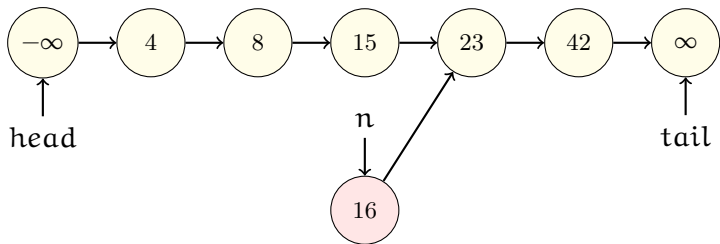
- Search for item without locking



# List-based set with lazy synchronization

Linearization of unsuccessful `contains(16)` call

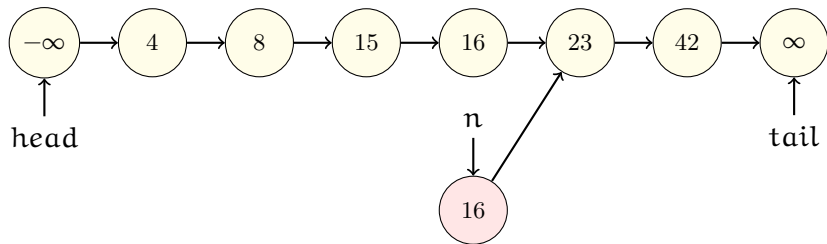
- Search for item without locking
- Node is unlinked by another thread



# List-based set with lazy synchronization

Linearization of unsuccessful `contains(16)` call

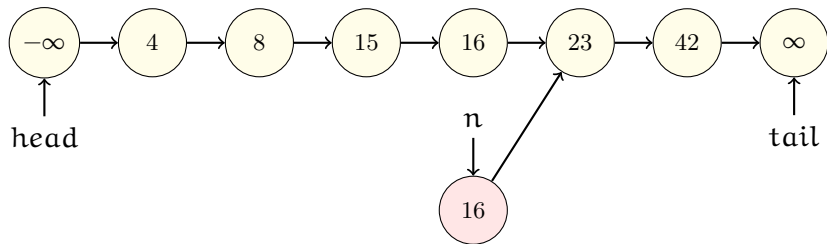
- Search for item without locking
- Node is unlinked by another thread
- Same value node is linked by another thread



# List-based set with lazy synchronization

Linearization of unsuccessful `contains(16)` call

- Search for item without locking
- Node is unlinked by another thread
- Same value node is linked by another thread
- `contains` call must be linearized before the check of the marked flag!





## Item not in list

`add` Successful validation of next node

`remove` Successful validation of next node

`contains` Earlier of

- Point where a removed matching node, or a node with `node->item > item` is found
- Point immediately before a new matching node is added to list

Linearization at the point where the marked flag is checked would be wrong, since this can be after a new node with same key is added. The point immediately before the new node is added is correct, since this `add` operation must be concurrent with the `contains` call (otherwise, `contains` would have found the item).

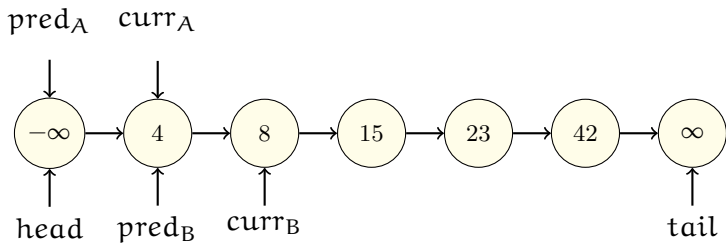
**Lesson:** Linearization point is not always some predetermined instruction!

Idea: Use `compare_exchange` to update `next`-pointer when adding and removing items.

## Does not work!

- Case 1: Thread A removes first item, thread B adds new second item. Both successfully perform `compare_exchange`, but B's item is not added
- Case 2: Thread A removes first item, thread B removes second item. Both successfully perform `compare_exchange`, but only the first item is removed

# Concurrent remove(4), remove(8)



# Making the list-based set lock-free

Idea: Use `compare_exchange` to update `next`-pointer when adding and removing items.

Repair:

- Treat `next`-pointer and `marked`-flag as an atomic unit.
- `compare_exchange` operation succeeds only if both pointer and flag have the expected value
- Marked nodes cannot be traversed, but must be linked out during traversal by `add` and `remove` operations

In absence of double-word compare-and-swap, steal a bit from the pointer and use that as flag. Addresses are normally less than full 64 bits (48 bits, 32 bits, ...)

# Marked pointer implementation

Take some free (upper) bits from pointer (**next** field in **Node**); use bit operations to read out and modify flag.

```
void *getpointer(void *); // mask out pointer part
bool getflag(void *);    // return stolen bit from next pointer
void setflag(void **);  // set bit in next pointer
void resetflag(void **); // reset bit in next pointer
```

Note: In code snippets masking out the pointer is mostly left out

Java: Use atomic marked reference

# Lock-free list-based set

```
Node* head;
struct Window {
    Node* pred;
    Node* curr;
}

bool contains(T item) {
    // same as lazy implementation
    // except marked flag is part of next
    // pointer
    Node* n = head;

    while (n->item < item)
        n = getpointer(n->next);

    return n->item == item &&
        !getflag(n->next);
}
```

```
Window find(T item) {
    // Search for item or successor
    retry: while (true) {
        Node* pred = head;
        Node* curr =
            getpointer(pred->next);

        while (true) {
            Node *succ =
                getpointer(curr->next);
            while (getflag(curr->next)) {
                // link out marked item (curr)

                resetflag(&curr);
                resetflag(&succ);
                if (!compare_exchange(
                    &pred->next, &curr, succ))
                    goto retry;

                curr = succ;
                succ = getpointer(succ->next);
            }

            if (curr->item >= item) {
                Window w(pred, curr);
                return w;
            }
            pred = curr;
            curr = getpointer(curr->next);
        }
    }
}
```

# Lock-free list-based set

```
bool add(T item) {
    Window w;

    while (true) {
        w = find(item);
        Node *pred = w.pred;
        Node *curr = w.curr;

        if (curr->item == item)
            return false;

        Node *n = new Node(item);
        n->next = curr;

        // unmark new node
        resetflag(&n->next);
        resetflag(&curr);

        if (compare_exchange(
            &pred->next, &curr, n))
            return true;
    }
}
```

```
bool remove(T item) {
    Window w;
    while (true) {
        w = find(item);
        if (item != w.curr->item)
            return false;

        Node *succ = w.curr->next;
        Node *markedsucc = succ;
        // mark as deleted
        setflag(&markedsucc);
        resetflag(&succ);
        if (!compare_exchange(&w.curr->next,
                               &succ,
                               markedsucc))

            continue;

        // attempt to unlink curr
        compare_exchange(&w.pred->next,
                        &w.curr, succ);

        return true;
    }
}
```

- Nodes may be traversed even though they have been removed
- We rely on garbage collection for removed nodes
- Sentinels are never added or removed
- Nodes are sorted by the item
- Each item occurs exactly once
- An item is in the set iff it is reachable from head and not marked



- `add` is lock-free
- `remove` is lock-free
- `contains` is wait-free

Argument: If a `compare_exchange` in `add` or `remove` fails, then some other thread has made progress.

Linearization points:

Outcome: Item in set

add Earlier of

- Point where found node is checked against `item`
- Point immediatly before node is marked

remove Compare-exchange on marked flag

contains Read of marked flag

Linearization points:

Outcome: Item not in set

add Compare-exchange

remove Earlier of

- Point where found node is checked against `item`
- Point immediatly before new node is inserted

contains Earlier of

- Point where a removed matching node, or a node with `node->item > item` is found
- Point immediatly before a new matching node is added to list

Which implementation works best depends on the use-case, all ideas have merits and drawbacks.

- Coarse-grained synchronization (lock, synchronized regions, ...) can be used with any (sequentially efficient!) data structure (black box). Can easily become bottleneck when data structure operations are frequent
- All other implementations require deep knowledge of the data structure implementation, need care to achieve correctness, liveness (deadlock-freedom), and performance
- Lock- and wait-free data structures provide theoretically best progress guarantees, but come at a cost (expensive atomic operations, frequent need to restart validation)

- Maged M. Michael. High performance dynamic lock-free hash tables and list-based sets. In Fourteenth Annual ACM Symposium on Parallel Algorithms and Architectures (SPAA), pages 73–82, 2002.